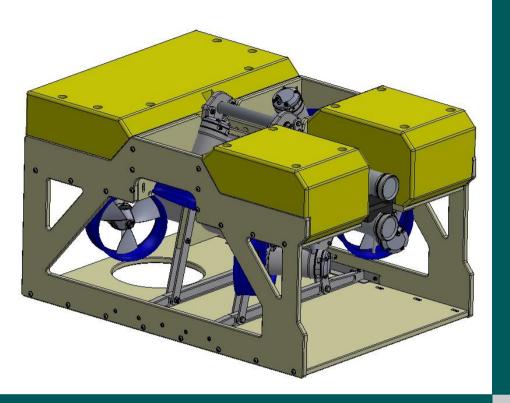
# Macduff Robotics

Intelligent Subsea Equipment



## **Description:**

A powerful electric ROV built for aggressive offshore applications. Capable of operating at depths of up to 1000m in free flying setup, and 3000m with a TMS.

# Rhaegal electric ROV

## MAIN FEATURES

- Powerful DC thrusters
- Lightweight frame
- High payload and expandability
- High electrical power availability for sensors and equipment

## **Further Information**

Advanced spares kits also available

# **Equipment supplied**

## Standard vehicle supply includes

- Vehicle assembly c/w load tested frame. 6 x ELT220 thrusters, tether junction box, thruster and JB compensators, tilt unit, and tilting camera mounting saddle.
- Topside power supply depending on configuration and system setup.
- Topside control PC. c/w vehicle control software.
- Topside control unit.
- Rack mounted power control and monitoring module.

## **Rhaegal Specifications**

Dimensions	
Length (mm)	1200
Width (mm)	850
Height (mm)	700
Depth Rating (m)	3000
Weight in Air (Kg)	400
Payload Capacity (Kg)	120
Power	15kW
Thrusters Horizontal (mmØ)	4 x ELT220
Thrusters Vertical (mmØ)	2 x ELT220
Bollard Pull (Nominal)	
Forward (Kgf)	160
Lateral (Kgf)	160
Vertical (Kgf)	100
Surface Speed (nominal)	4.1 Knots

#### Standard System Equipment

- Fiber optic telemetry
- Twin Camera Tilt Unit
- 3off LED Light units
- Depth Transducer
- Recovery Lift Point

#### **Optional Equipment**

- Cameras various third party options.
- HD cameras various third party options.
- Sonar unit various third party options.
- Altimeter
- CP Probe
- 3 Function Electric Manipulator
- Hydraulic power unit
- Cleaning Brush
- Acoustic Transponder
- Recovery Beacon and Flasher
- Recovery Bullet & Lock Latch
- Auto-positioning features (station keeping, waypoint following, return to location) when suitable DVL and gyrocompass are fitted.

### **Control System**

 Windows PC based control system with power management, diagnostics and auto-position capability

#### **Features**

- Windows Based Software
- Graphical status and fault locator
- Real-time Optical Multiplexer, video condition and fault monitoring
- User preset positioning of Camera tilt unit

#### Telemetry

- 2 x Real-time PAL & NTSC video channels
- Spare digital and analogue I/O's dependent on requirements and equipment fitted.
- Ethernet/RS232 option

### Additional System options

- Electric or hydraulic storage Winch
- Control Cabin
- Certified/Zone rated Winch/Cabin
- Integrated Pilot Chair
- Graphics/Vision/Sonar monitors
- Video Overlay/Switching/Recording
- Workskids (Tooling, Survey, etc)

